## Searches for User gphilippe (Count = 2127)

Queries 2078 through 2127.

Fin	6		
	63.6	Next	Oldest
E	iii He	p Ret	urn

S# Upd	t	Database	Query	Time	Comment
<u>S2127</u> <u>U</u>	USPT		(size with stream\$ same image with dislay\$2)	2005-06- 09	
				12:14:34	
<u>S2126 U</u>	USPT		5805762.pn.	2005-06- 09 11:33:51	
<u>S2125</u> <u>U</u>	USPT		weight\$ and ((decod\$3 with priorit\$5) same streams)	2005-06- 09 11:13:58	
<u>S2124</u> <u>U</u>	USPT		((decod\$3 with priorit\$5) same streams)		
<u>S2123</u> <u>U</u>	USPT	·	chang\$3 and weight\$ and ((priorit\$5 with (decoding or decoder or decode\$1)) same streams)	2005-06- 09 11:09:57	
<u>S2122</u> <u>U</u>	USPT		weight\$ and ((priorit\$5 with (decoding or decoder or decode\$1)) same streams)	2005-06- 09 11:09:29	
<u>S2121</u> <u>U</u>	USPT		((priorit\$5 with (decoding or decoder or decode\$1)) same streams)	2005-06- 09 11:09:14	
<u>S2120</u> <u>U</u>	USPT		(adaptiv\$ with (setting or set\$1)) and ((changing or change\$1) same priorit\$) and ((priorit\$5 with decod\$3) same (setting or sets or set)) and streams	2005-06- 09 11:02:25	
<u>\$2119</u> <u>U</u>	USPT		((changing or change\$1) same priorit\$) and ((priorit\$5 with decod\$3) same (setting or sets or set)) and streams	2005-06- 09 11:01:30	
<u>S2118</u> <u>U</u>	USPT		((priorit\$5 with decod\$3) same (setting or sets or set)) and streams	2005-06- 09 11:00:41	6

<u>S2117</u>	<u>U</u>	USPT	(5353061 or 6404461 or	2005-06-
			4805123 or 6307888).pn.	08 18:42:13
S2116	U	USPT	(5353061 or 6404461 or	2005-06-
3211			4805123 6307888).pn.	08
			•	18:42:00
<u>S2115</u>	U	USPT	(pixels with difference) and	2005-06-
			phong shading model	08
				17:25:37
<u>S2114</u>	<u>U</u>	USPT	radiance and pixels and phong	2005-06-
			shading model	08 17:25:11
S2113	TT	USPT	nivels and phone shading model	
32113	<u>U</u>	USFI	pixels and phong shading model	08
				17:25:02
S2112	U	USPT	phong shading model	2005-06-
	<u></u>		prong samong model	08
				17:24:22
<u>S2111</u>	<u>U</u>	USPT	phong and 5353061.pn.	2005-06-
				08
				17:24:06
<u>S2110</u>	<u>U</u>	USPT	background and 5353061.pn.	2005-06-
				08
22100		LIGHM		15:55:37
<u>S2109</u>	<u>U</u>	USPT	(temporal\$ or adjacent) and	2005-06-
			5353061.pn.	08 15:35:22
S2108	U	PGPB,USPT,EPAB,JPAB,DWPI	(temporals or adjacent) and	2005-06-
52100	$\underline{\mathbf{v}}$	TOLD, COLL, LI MD, JI MD, D WI I	5353061.pn.	08
				15:35:11
S2107	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWPI	(temporal\$ or adjacent) and	2005-06-
			5353061.pn.	08
				15:34:58
<u>S2106</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWPI	noise and 5353061.pn.	2005-06-
				08
50105	TT	DCDD LIGDT ED A D ED A D DYVDI	· / · 101 1 .05 1	13:47:42
<u>S2105</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWPI		2005-06-
			5353061.pn.	08 13:37:44
S2104	U	PGPB,USPT,EPAB,JPAB,DWPI	camera\$1 and 5353061 nn	2005-06-
<u> </u>	<u>u</u>	1010,0011,01710,01710,0 1111	camera and 3333001.pm.	08
				13:30:18
S2103	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWPI	(difference with map\$4) and	2005-06-
			(camera same noise level) and	08
			(frame\$1 with difference\$1)	12:52:32
<u>S2102</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWPI		2005-06-
			(frame\$1 with difference\$1)	08
				12:52:02

<u>S210</u>	1 !	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWPI	(camera and noise) and 5353061 pn.	2005-06- 08 12:49:51
<u>S210</u>	<u>0</u> · <u>1</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWPI	(camera same noise) and 5353061.pn.	2005-06- 08
<u>S209</u>	9 ]	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWPI	(camera with noise) and 5353061.pn.	12:49:40 2005-06- 08
<u>S209</u>	<u>8</u> ]	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWPI	illuminat\$ and ((difference with map\$1) same image\$1) and (pixel\$1 with locat\$4) and	12:49:23 2005-06- 08 12:20:29
S209	<u>7</u> <u>1</u>	<u>U</u>		(camera with noise) ((difference with map\$1) same image\$1) and (pixel\$1 with locat\$4) and (camera with	2005-06- 08 12:19:31
S209	<u>6</u> <u>1</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWPI	with differenc\$3)) and map\$4	2005-06- 08
S209	<u>5</u> <u>1</u>	<u>U</u>	USPT	and (noise with level\$1) ((camera with noise) and (difference map\$1 same	12:14:49 2005-06- 07
S209	<u>4</u> <u>1</u>	<u>U</u>	USPT	image\$1) and illuminat\$) ((camera with noise level) and (difference map\$1 same	18:02:41 2005-06- 07
S209	<u>3</u> <u>1</u>	<u>U</u>	USPT	image\$1) and illuminat\$) ((camera with noise level) and (difference map\$1 same	18:02:24 2005-06- 07
S209	<u>2</u> <u>1</u>	<u>U</u>	USPT	image\$1) and (sudden\$ with illuminat\$)) difference map\$1 and illuminat\$ and pixel\$1 and	18:01:52 2005-06- 07
<u>S209</u>	<u>1</u> <u>U</u>	<u>U</u>		noise and locat\$4 edit\$ and 5831688.pn.	17:27:35 2005-06- 07
S209	<u>0</u> <u>I</u>	<u>U</u>		(edit\$ or index\$) and 5831688.pn.	15:01:42 2005-06- 07
S2089	9 <u>I</u>	<u>U</u>		(transcoding or re-encod\$ or reencod\$ or re encod\$) and	15:00:20 2005-06- 07
S208	<u>8</u> <u>I</u>	<u>U</u>		6735253.pn. global\$ and 6735253.pn.	14:51:42 2005-06- 07
S208'	<u>7</u> <u>I</u>	<u>U</u>		((adaptive near3 motion compensat\$) same (global motion compensat\$) same	14:43:56 2005-06- 06 18:01:00

		(motion parameter\$1) and information)	
<u>S2086</u> <u>U</u>	USPT	information and global motion compensat\$ and (adaptive\$ with motion compensation)	2005-06- 06 17:54:20
<u>S2085</u> <u>U</u>	USPT	global motion compensat\$ and (adaptive\$ with motion	2005-06- 06
<u>S2084</u> <u>U</u>	USPT	compensation) (adaptive\$ with motion compensation)	17:54:05 2005-06- 06
<u>S2083</u> <u>U</u>	USPT	adaptive\$ and 6735253.pn.	17:49:53 2005-06- 06
<u>S2082</u> <u>U</u>	USPT	adaptive\$ and 5831688.pn.	17:42:09 2005-06- 06
<u>S2081</u> <u>U</u>	USPT	(transcod\$ or reencod\$ or re encod\$) and ((adaptive\$ with	17:41:38 2005-06- 06
		motion compensat\$) and global motion compensat\$ and motion parameter\$1) and information	17:30:39
<u>S2080</u> <u>U</u>	USPŤ	(transcod\$ or reencod\$ or re encod\$) and bit rate\$1 and	2005-06- 06
		((adaptive\$ with motion compensat\$) and global motion compensat\$ and motion parameter\$1) and information	17:30:12
<u>S2079</u> <u>U</u>	USPT	bit rate\$1 and ((adaptive\$ with motion compensat\$) and global	06
<u>S2078 U</u>	HSPT	motion compensat\$ and motion parameter\$1) and information ((adaptive\$ with motion	2005-06-
32076 0	OSI I	compensat\$) and global motion compensat\$ and motion parameter\$1) and information	

